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/*****
Module
    Transmit_Service.c

Revision
    1.0.1

Description
    Contains All Functions to Assist with Transmitting Data via XBEE
*****/
/*----- Include Files -----*/
/* include header files for this state machine as well as any machines at the
   next lower level in the hierarchy that are sub-machines to this machine
*/
#include <stdio.h>
#include <string.h>
#include "ES_Configure.h"
#include "ES_Framework.h"
#include "Transmit_Service.h"
#include "Outputs_Service.h"
#include "Definitions.h"
#include "Master_SM.h"
#include "Receive_SM.h"

/*----- Module Defines -----*/
#define ENCR_RAND_MAX 255;

/*----- Module Functions -----*/
/* prototypes for private functions for this service.They should be functions
   relevant to the behavior of this service
*/

void setCurrentTransmitPacket(uint8_t *packet, uint8_t length);

/*----- Module Variables -----*/
// with the introduction of Gen2, we need a module level Priority variable
static uint8_t MyPriority;

//Create Array with Prologues
uint8_t TX_Packet_Prologue_STAT[PROLOGUE_TRANSMIT_LENGTH] = {START_DELIMITER,
                                                             ZERO_BYTE,
                                                             STATUS_LENGTH,
                                                             API_IDENTIFIER_SEND,
                                                             ZERO_FRAME_ID,
                                                             BROADCAST_1,
                                                             BROADCAST_2,
                                                             OPTIONS_ACK};

static uint8_t CurrentTransmitPacketLength = PROLOGUE_TRANSMIT_LENGTH +
                                              STAT_LENGTH + CHECKSUM_LENGTH;
                                              //Initialize the length of the
                                              current transmit packet

static uint8_t StatTransmitPacket[PROLOGUE_TRANSMIT_LENGTH + STAT_LENGTH +
CHECKSUM_LENGTH] = {START_DELIMITER, ZERO_BYTE, STATUS_LENGTH,
API_IDENTIFIER_SEND, ZERO_FRAME_ID, BROADCAST_1, BROADCAST_2, OPTIONS_ACK,
STATUS_HDR, ZERO_BYTE, ZERO_BYTE, ZERO_BYTE}; //Set the Current Transmit Packet
Equal to the Maximum Value

static uint8_t CurrentTransmitPacketIndex; //Initialize the current index of
the
transmit packet

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static uint8_t CurrentTransmitPacketDestinationMSB;
static uint8_t CurrentTransmitPacketDestinationLSB;

/*----- Module Code -----*/
/*****
Function
    InitTransmit_Service

Parameters
    uint8_t : the priority of this service

Returns
    bool, false if error in initialization, true otherwise

Description
    Initializes the Transmit Service
*****/
bool InitTransmit_Service ( uint8_t Priority )
{
    ES_Event ThisEvent;

    MyPriority = Priority;

    // post the initial transition event
    ThisEvent.EventType = ES_INIT;
    if (ES_PostToService( MyPriority, ThisEvent) == true)
    {
        return true;
    }
    else
    {
        return false;
    }
}

/*****
Function
    PostTransmit_Service

Parameters
    EF_Event ThisEvent ,the event to post to the queue
*****/
bool PostTransmit_Service( ES_Event ThisEvent )
{
    return ES_PostToService( MyPriority, ThisEvent);
}

/*****
Function
    RunTransmit_Service

Parameters
    ES_Event : the event to process

Returns
    ES_Event, ES_NO_EVENT if no error ES_ERROR otherwise

Description
*****/
ES_Event RunTransmit_Service( ES_Event ThisEvent )

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{
    ES_Event ReturnEvent;
    ReturnEvent.EventType = ES_NO_EVENT; // assume no errors
    /*****
    in here you write your service code
    *****/
    return ReturnEvent;
}

/*****
private functions
*****/

void sendStatus(void)
{
    CurrentTransmitPacketIndex = 0;
    //Set the Destination Bits of the Prologue
    StatTransmitPacket[TX_INDEX_DESTINATION_MSB] = CurrentTransmitPacketDestinati
onMSB;
    StatTransmitPacket[TX_INDEX_DESTINATION_LSB] = CurrentTransmitPacketDestinati
onLSB;
    StatTransmitPacket[TX_INDEX_HEADER+1] = getCurrentStatus();
    StatTransmitPacket[TX_INDEX_HEADER+2] = getLastEncryptedChecksum();

    //Send the First Byte
    sendNextByte();
}

//Set the destination of the transmit packet
void setTransmitPacketDestinationMSB(uint8_t MSB)
{
    CurrentTransmitPacketDestinationMSB = MSB;
}

void setTransmitPacketDestinationLSB(uint8_t LSB)
{
    CurrentTransmitPacketDestinationLSB = LSB;
}

//Send Next Byte to UART
bool sendNextByte(void)
{
    static uint8_t checkSum; //initialize static variable for checksum

    //Check if this is the last byte
    if (CurrentTransmitPacketIndex == (CurrentTransmitPacketLength - 1))
    {
        StatTransmitPacket[CurrentTransmitPacketIndex] = 0xff - checkSum;
    }

    //Write the Current Byte to the UART Register
    HWREG(UART1_BASE + UART_O_DR) = StatTransmitPacket[
        CurrentTransmitPacketIndex];
    //printf("Tx: %x\n\r", StatTransmitPacket[CurrentTransmitPacketIndex]);

    //Calculate the CheckSum
    if (CurrentTransmitPacketIndex >= TX_INDEX_API)
    {
        checkSum += StatTransmitPacket[CurrentTransmitPacketIndex];
    }
}

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//Increment the index
CurrentTransmitPacketIndex++;

//If it was the first byte being transmitted enable TXIM
if (CurrentTransmitPacketIndex == 1)
{
    HWREG(UART1_BASE + UART_O_IM) |= (UART_IM_TXIM);
}
else if (CurrentTransmitPacketIndex == (CurrentTransmitPacketLength))
    //if last byte return true
{
    checkSum = 0;//Reset the checksum
    return true;
}

//If Not Return False
return false;
}

/*----- Footnotes -----*/
/*----- End of file -----*/
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